

Riemannian Geometry IV

Solutions, set 5.

Exercise 10.

(a) Let $p = (X, Y, Z) \in \mathbb{W}^2$. Then

$$L_p = \{(X, Y, Z) + t(X, Y, Z + 1) \mid t \in \mathbb{R}\}$$

and

$$L_p \cap \mathbb{B}^2 = (X, Y, Z) - \frac{Z}{Z+1}(X, Y, Z+1) = \left(\frac{X}{Z+1}, \frac{Y}{Z+1}, 0\right).$$

We conclude that

$$f(X, Y, Z) = \left(\frac{X}{Z+1}, \frac{Y}{Z+1}, 0\right) \in \mathbb{B}^2.$$

Conversely, let $f^{-1}(x, y, 0) = (X, Y, Z)$ with $X^2 + Y^2 = Z^2 - 1$. Since $x = \frac{X}{Z+1}$, $y = \frac{Y}{Z+1}$, we conclude that

$$x^2 + y^2 = \frac{X^2 + Y^2}{(Z+1)^2} = \frac{Z^2 - 1}{(Z+1)^2} = \frac{Z-1}{Z+1},$$

so $Z = \frac{1+x^2+y^2}{1-x^2-y^2}$ and $Z+1 = \frac{2}{1-x^2-y^2}$. We conclude that

$$\begin{aligned} f^{-1}(x, y, 0) &= (X, Y, Z) = ((Z+1)x, (Z+1)y, Z) \\ &= \left(\frac{2x}{1-x^2-y^2}, \frac{2y}{1-x^2-y^2}, \frac{1+x^2+y^2}{1-x^2-y^2}\right). \end{aligned}$$

(b) We have

$$\psi^{-1}(y_1, y_2) = f \circ \varphi^{-1}(y_1, y_2) = \left(\frac{\sinh y_2}{1 + \cosh y_2} \cos y_1, \frac{\sinh y_2}{1 + \cosh y_2} \sin y_1, 0\right).$$

(c) Let $p = \varphi^{-1}(x_1, x_2) = (\cos x_1 \sinh x_2, \sin x_1 \sinh x_2, \cosh x_2)$. Then $f(p) = \psi^{-1}(x_1, x_2)$, so $y_1 = x_1, y_2 = x_2$. So

$$f(p) = \left(\frac{\sinh x_2}{1 + \cosh x_2} \cos x_1, \frac{\sinh x_2}{1 + \cosh x_2} \sin x_1, 0 \right).$$

Moreover, we have

$$\begin{aligned} \left. \frac{\partial}{\partial y_1} \right|_{f(p)} &= \frac{1}{1 + \cosh x_2} (-\sinh x_2 \sin x_1, \sinh x_2 \cos x_1, 0), \\ \left. \frac{\partial}{\partial y_2} \right|_{f(p)} &= \frac{1}{1 + \cosh x_2} (\cos x_1, \sin x_1, 0). \end{aligned}$$

We know from Example 14 (a) that

$$\begin{aligned} \left\langle \left. \frac{\partial}{\partial x_1} \right|_p, \left. \frac{\partial}{\partial x_1} \right|_p \right\rangle_p &= \sinh^2 x_2, \\ \left\langle \left. \frac{\partial}{\partial x_1} \right|_p, \left. \frac{\partial}{\partial x_2} \right|_p \right\rangle_p &= 0, \\ \left\langle \left. \frac{\partial}{\partial x_2} \right|_p, \left. \frac{\partial}{\partial x_2} \right|_p \right\rangle_p &= 1. \end{aligned}$$

We obviously have

$$\left\langle \left. \frac{\partial}{\partial y_1} \right|_{f(p)}, \left. \frac{\partial}{\partial y_2} \right|_{f(p)} \right\rangle_{f(p)} = 0.$$

Since

$$\|f(p)\|_0^2 = \frac{\sinh^2 x_2}{(1 + \cosh x_2)^2},$$

(where $\|\cdot\|_0$ denotes the standard Euclidean norm,) we conclude that

$$1 - \|f(p)\|_0^2 = \frac{2}{1 + \cosh x_2}.$$

We calculate

$$\begin{aligned} \left\langle \left. \frac{\partial}{\partial y_1} \right|_{f(p)}, \left. \frac{\partial}{\partial y_1} \right|_{f(p)} \right\rangle_{f(p)} &= \\ \frac{4}{(1 - \|f(p)\|_0^2)^2} \frac{1}{(1 + \cosh x_2)^2} \left\| (-\sinh x_2 \sin x_1, \sinh x_2 \cos x_1, 0) \right\|_0^2 &= \\ \sinh^2 x_2 \sin^2 x_1 + \sinh^2 x_2 \cos^2 x_1 &= \sinh^2 x_2. \end{aligned}$$

Similarly, we obtain

$$\left\langle \frac{\partial}{\partial y_2} \Big|_{f(p)}, \frac{\partial}{\partial y_2} \Big|_{f(p)} \right\rangle_{f(p)} = \frac{4}{(1 - \|f(p)\|_0^2)^2} \frac{1}{(1 + \cosh x_2)^2} \|(\cos x_1, \sin x_1, 0)\|_0^2 = \cos^2 x_1 + \sin^2 x_1 = 1.$$

Exercise 11.

(a) We calculate

$$\begin{aligned} Df_A(z)(v) &= \frac{d}{dt} \Big|_{t=0} f_A(z + tv) = \frac{d}{dt} \Big|_{t=0} \frac{a(z + tv) + b}{c(z + tv) + d} \\ &= \frac{av(cz + d) - (az + b)cv}{(cz + d)^2} = \frac{(ad - bc)v}{(cz + d)^2} = \frac{1}{(cz + d)^2} v, \end{aligned}$$

where we used in the last step that $\det A = ad - bc = 1$. The imaginary part of $f_A(z)$ is related to the imaginary part of z in the following way:

$$\begin{aligned} \operatorname{Im}(f_A(z)) &= \operatorname{Im} \left(\frac{az + b}{cz + d} \right) = \operatorname{Im} \left(\frac{(az + b)(c\bar{z} + d)}{|cz + d|^2} \right) \\ &= \frac{1}{|cz + d|^2} \operatorname{Im}(adz + bc\bar{z} + ac|z|^2 + bd) = \frac{(ad - bc)\operatorname{Im}(z)}{|cz + d|^2} = \frac{\operatorname{Im}(z)}{|cz + d|^2}. \end{aligned}$$

We conclude that

$$\begin{aligned} g_{f_A(z)}(Df_A(z)(v), Df_A(z)(v)) &= \frac{1}{\operatorname{Im}(f_A(z))^2} \frac{1}{|cz + d|^4} \langle v, v \rangle \\ &= \frac{|cz + d|^4}{\operatorname{Im}(z)} \frac{1}{|cz + d|^4} \langle v, v \rangle = \frac{1}{\operatorname{Im}(z)} \langle v, v \rangle = g_z(v, v), \end{aligned}$$

so f_A is an isometry.

(b) One easily checks that $f_{A_1}(z) = z + x$ and $f_{A_2}(z) = yz$ for $A_1 = \begin{pmatrix} 1 & x \\ 0 & 1 \end{pmatrix}$ and $A_2 = \begin{pmatrix} y^{1/2} & 0 \\ 0 & y^{-1/2} \end{pmatrix}$. The group action property tells us then that

$$f_{A_1 A_2}(i) = f_{A_1} \circ f_{A_2}(i) = f_{A_1}(iy) = x + iy \in \mathbb{H}^2,$$

which means that $\{f_A(i) \mid A \in SL(2, \mathbb{R})\} = \mathbb{H}^2$.

(c) First let $A = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix}$ be an arbitrary matrix in $SO(2)$. Then

$$f_A(i) = \frac{i \cos \alpha + \sin \alpha}{-i \sin \alpha + \cos \alpha} = (\sin \alpha + i \cos \alpha)(\cos \alpha + i \sin \alpha) = i.$$

Conversely, let $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$ be such that

$$f_A(i) = \frac{ai + b}{ci + d} = i.$$

Then $ai + b = -c + di$, i.e., $a = d$ and $b = -c$. Moreover, $1 = ad - bc = a^2 + b^2$. Therefore, there exists $\alpha \in [0, 2\pi)$ such that $a = \cos \alpha$ and $b = \sin \alpha$ and

$$A = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} \in SO(2).$$

Exercise 12. T^2 is the rotation of a circle in the (X, Z) -plane with centre $(R, 0, 0)$ and radius $r > 0$ around the vertical Z -axis.

We first note that

$$\begin{aligned} \frac{\partial}{\partial x_1} \Big|_{\varphi^{-1}(x_1, x_2)} &= (-r \sin x_1 \cos x_2, -r \sin x_1 \sin x_2, r \cos x_1), \\ \frac{\partial}{\partial x_2} \Big|_{\varphi^{-1}(x_1, x_2)} &= (-(R + r \cos x_1) \sin x_2, (R + r \cos x_1) \cos x_2, 0). \end{aligned}$$

This implies that

$$(g_{ij}(\varphi^{-1}(x_1, x_2))) = \begin{pmatrix} r^2 & 0 \\ 0 & (R + r \cos x_1)^2 \end{pmatrix}.$$

So $\sqrt{\det(g_{ij}(\varphi^{-1}(x_1, x_2)))} = r(R + r \cos x_1)$. Since $\varphi^{-1}(V) = U \subset T^2$ covers all of T^2 except a set of measure zero, we obtain

$$\begin{aligned} \text{vol}(T^2) &= \text{vol}(U) = \int_V r(R + r \cos x_1) dx_1 dx_2 \\ &= \int_0^{2\pi} \int_0^{2\pi} r(R + r \cos x_1) dx_1 dx_2 = 4\pi^2 r R. \end{aligned}$$

Exercise 13. The formula for the hyperbolic volume yields

$$\begin{aligned}
\text{vol}(\Delta P_1 P_2 P_3) &= \int_{x_1}^{x_2} \int_{\sqrt{r^2 - (x-x_0)^2}}^{\infty} \frac{dy}{y^2} dx = \int_{x_1}^{x_2} \frac{1}{y} \Big|_{\infty}^{\sqrt{r^2 - (x-x_0)^2}} dx \\
&= \int_{x_1}^{x_2} \frac{1}{\sqrt{r^2 - (x-x_0)^2}} dx = \frac{1}{r} \int_{x_1}^{x_2} \frac{1}{\sqrt{1 - \left(\frac{x-x_0}{r}\right)^2}} dx \\
&= \frac{1}{r} \int_{x_1-x_0}^{x_2-x_0} \frac{1}{\sqrt{1 - \left(\frac{x}{r}\right)^2}} dx = \int_{\frac{x_1-x_0}{r}}^{\frac{x_2-x_0}{r}} \frac{dy}{\sqrt{1-y^2}} \\
&= \arcsin\left(\frac{x_2-x_0}{r}\right) - \arcsin\left(\frac{x_1-x_0}{r}\right) = \arcsin\left(\frac{x_2-x_0}{r}\right) + \arcsin\left(\frac{x_0-x_1}{r}\right).
\end{aligned}$$

The picture implies that $\cos \alpha = \frac{x_0-x_1}{r}$. Since $\alpha \in (0, \pi/2)$, we have

$$\alpha = \arccos\left(\frac{x_0-x_1}{r}\right).$$

Similarly, we conclude that

$$\beta = \arccos\left(\frac{x_2-x_0}{r}\right).$$

Using $\arcsin(x) + \arccos(x) = \pi/2$ we finally obtain the desired formula:

$$\begin{aligned}
\text{vol}(\Delta P_1 P_2 P_3) &= \arcsin\left(\frac{x_2-x_0}{r}\right) + \arcsin\left(\frac{x_0-x_1}{r}\right) \\
&= \pi - \arccos\left(\frac{x_2-x_0}{r}\right) - \arccos\left(\frac{x_0-x_1}{r}\right) = \pi - \alpha - \beta.
\end{aligned}$$