

Existence and stability of stationary fronts in inhomogeneous wave equations

Gianne Derks*

University of Surrey, Guildford, UK

Joint research with Arjen Doelman, Giuseppe Gaeta, Chris Knight and
Hadi Susanto

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Maths research at Surrey

Introduction sG Stability DNA Discussion

At the interface between pure and applied mathematics



Biosystems

- Ecology and Evolutionary Biology
- Biophysics
- Metabolism
- Statistics



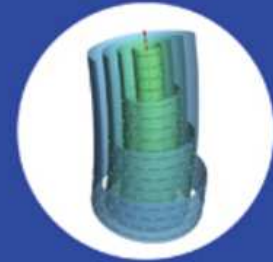
Dynamical Systems and PDEs

- Nonlinear PDEs
- Dynamical Systems
- Calculus of Variations
- Geometry and Mechanics



Fields, Strings and Geometry

- Quantum Fields, String/M-Theory and Supergravity
- Dualities (AdS/CFT,...)
- Topological Strings
- Integrability, Twistor Geometry and Geometric Analysis



Fluid Mechanics and Meteorology

- Geometric Fluid Dynamics
- Mathematical Meteorology and Data Assimilation
- Water Waves
- Hydrodynamic Stability

Introduction

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Homogeneous nonlinear wave equations like

- $u_{tt} - u_{xx} - V'(u) = 0$ (e.g. $V'(u) = \sin u$, sine-Gordon);
- $i\psi_t + \psi_{xx} - f'(|\psi|^2)\psi = 0$ (e.g. $f'(|\psi|^2) = a + b|\psi|^2$, NLS);

often have (families of) travelling/stationary solitary waves or kinks.

Introduction

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Homogeneous nonlinear wave equations like

- $u_{tt} - u_{xx} - V'(u; x) = 0$ (e.g. $V'(u, x) = D(x) \sin u$, sine-Gordon);
- $i\psi_t + \psi_{xx} - f'(|\psi|^2; x)\psi = 0$ (e.g. $f'(|\psi|^2) = a(x) + b(x)|\psi|^2$, NLS);

often have (families of) travelling/stationary solitary waves or kinks.

What happens with these coherent structures if there are inhomogeneities (e.g. related to periodic media, external potentials, or interfaces)?

- Do the fronts/solitons persist?
- What about their stability?

In this talk, we consider an inhomogeneous sine-Gordon-like equation for

- superconductors: long Josephson junction with impurity;
- DNA-RNAP interaction.

Recap nonlinear homogeneous wave eqn

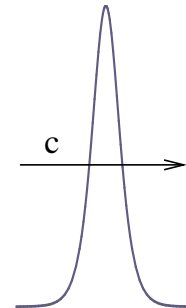
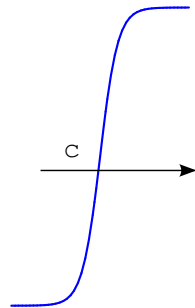
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A nonlinear (semi-linear) wave equation on the real line:

$$u_{tt} = u_{xx} + V'(u).$$

A travelling wave front or solitary wave solution is of the form

$$u(x, t) = \hat{u}(x - ct) \quad \text{and} \quad \lim_{|\xi| \rightarrow \infty} \hat{u}_\xi(\xi) = 0.$$



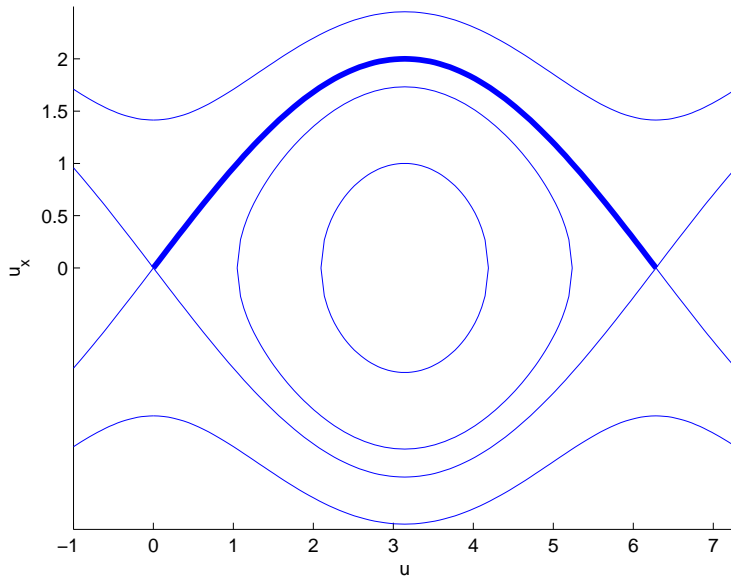
Existence and stability of such solutions?

Existence of fronts/solitary waves

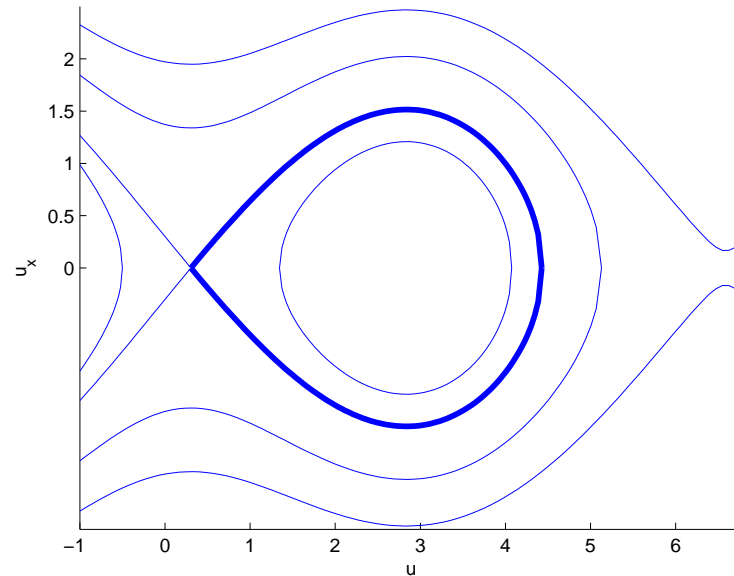
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Write $\xi = \frac{x-ct}{\sqrt{1-c^2}}$, then $\hat{u}(\xi)$ satisfies $\hat{u}_{\xi\xi} + V'(\hat{u}) = 0$, $\lim_{|\xi| \rightarrow \infty} \hat{u}_\xi(\xi) = 0$.

This is a Hamiltonian ODE, we can use phase plane analysis.



$$V(u) = \cos(u)$$



$$V(u) = \cos(u) + u/3$$

- Fronts correspond to heteroclinic connections;
- Solitary waves correspond to homoclinic connections.

Stability of fronts/solitary waves

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Linearise about the front/solitary wave: $u(x, t) = \hat{u}(\xi) + v(\xi, t)$ with $\xi = \frac{x-ct}{\sqrt{1-c^2}}$ and $v(\xi, t) = e^{\lambda t}v(\xi)$ gives the eigenvalue problem

$$\lambda^2 v = \mathcal{L}v, \quad \text{with} \quad \mathcal{L} = D_{\xi\xi} + V''(\hat{u}).$$

- This is a Sturm-Liouville problem, so the eigenfunction associated to the largest eigenvalue of \mathcal{L} has no zeros.
- Differentiating the ODE for \hat{u} with respect to ξ gives $\mathcal{L}\hat{u}_\xi = 0$. As \hat{u} is smooth, \hat{u}_ξ is an eigenfunction of \mathcal{L} with the eigenvalue zero.

Lemma *The front \hat{u} is nonlinearly stable iff \hat{u}_ξ has no zeros. The solitary wave \hat{u} is non-monotonic, hence unstable.*

To prove nonlinear stability, use the Hamiltonian

$$H(u, P) = \frac{1}{2} \int_{-\infty}^{\infty} [P^2 + u_\xi^2 - V(u)] d\xi.$$

Josephson junctions & sine-Gordon models

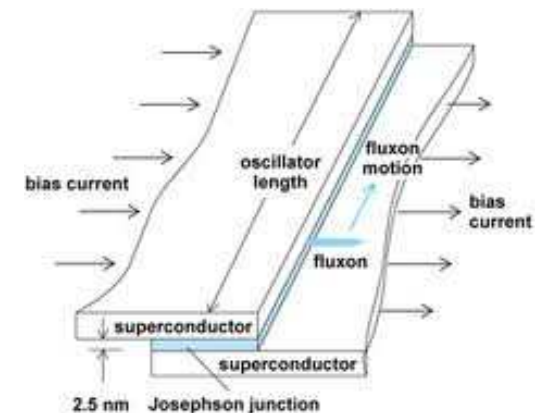
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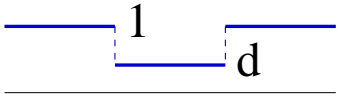
Propagation of the magnetic flux $\phi(x, t)$ in a long Josephson junction (LJJ) is described by an inhomogeneous perturbed sine-Gordon equation:

$$\phi_{tt} = \phi_{xxx} - D(x) \sin \phi + \gamma - \alpha \phi_t, \quad x \in \mathbb{R}, t > 0.$$

The meaning of the various terms:

- γ : induced current;
- $\alpha \geq 0$: dissipation;
- $D(x)$: magnetic variations/impurities:



- ◆ $D = 1$: long Josephson junction without variations/impurities;
- ◆ $D(x) = 1$, for $x < 0$ and $D(x) = -1$ for $x > 0$: 0 - π Josephson junction. Magnetic variation induces phase shift of π ;
- ◆ $D(x) = 1$ for $|x| > L$ and $D(x) = d > 0$ for $|x| < L$:  magnetic impurities;
- ◆ Combinations of above.

The perturbed sine-Gordon model

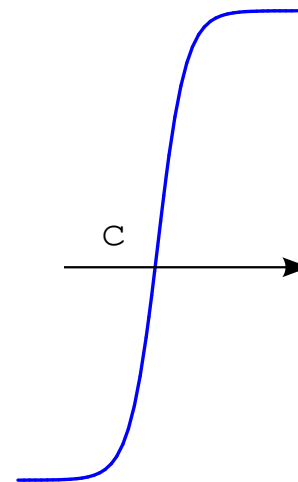
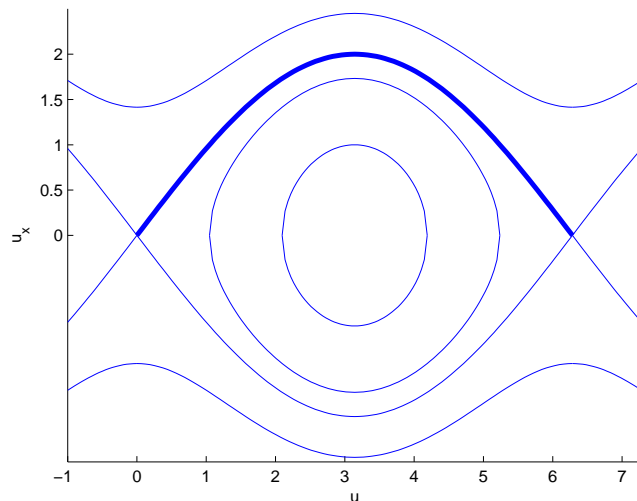
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No magnetic variations/impurities ($D = 1$): perturbed sine-Gordon equation

$$\phi_{tt} = \phi_{xx} - \sin \phi + \gamma - \alpha \phi_t, \quad x \in \mathbb{R}, t > 0.$$

Solutions:

- Fixed points are solutions of $\sin \phi - \gamma = 0$.
- If $\gamma = 0 = \alpha$, then it is the sine-Gordon equation. There is a family of stable travelling fronts ($|c| < 1$), called fluxons.



The perturbed sine-Gordon model

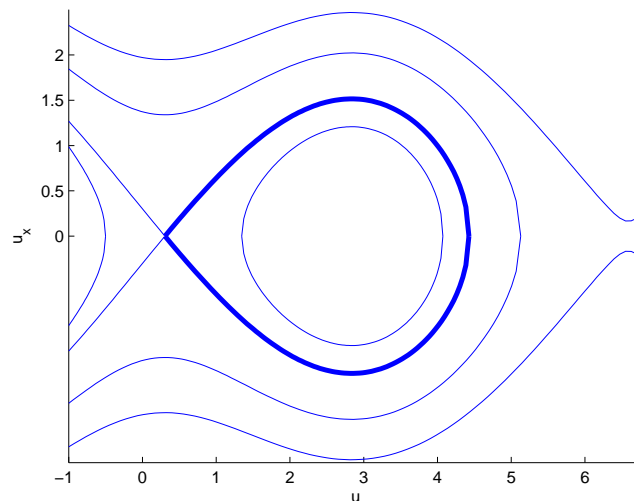
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- If $\gamma = 0 = \alpha$, then it is the sine-Gordon equation. There is a family of stable travelling fronts ($|c| < 1$), called fluxons.
- If $\alpha = 0, \gamma \neq 0$, then there are unstable travelling solitary waves.



The perturbed sine-Gordon model

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No magnetic variations/impurities ($D = 1$): perturbed sine-Gordon equation

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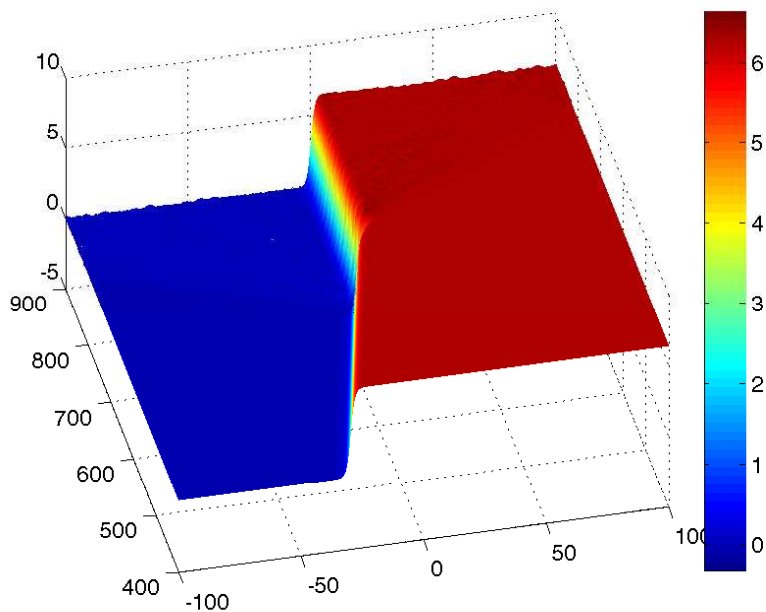
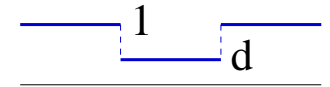
Solutions:

- Fixed points are solutions of $\sin \phi - \gamma = 0$.
- If $\gamma = 0 = \alpha$, then it is the sine-Gordon equation. There is a family of stable travelling fronts ($|c| < 1$), called fluxons.
- If $\alpha = 0, \gamma \neq 0$, then there are unstable travelling solitary waves.
- If $\gamma \neq 0, \alpha \neq 0$: there is one travelling fluxon with speed $c(\gamma, \alpha)$. This fluxon connects $\arcsin \gamma$ with $2\pi + \arcsin \gamma$ and is stable.

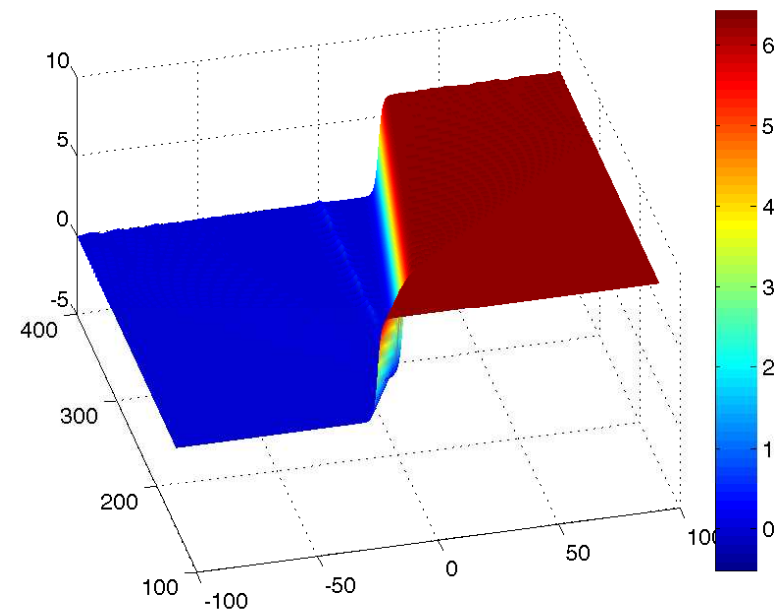
The effect of impurities

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What happens with the travelling fluxon if an impurity is present?



A slow-ish fluxon gets trapped.



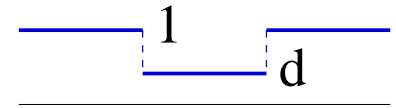
A faster fluxon gets slowed down.

- Questions:
- are there pinned fluxons?
 - if so, which ones are stable?

Sine-Gordon with impurity

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The sine-Gordon equation with an impurity:



$$\phi_{tt} = \phi_{xx} - D(x) \sin \phi + \gamma - \alpha \phi_t, \quad \text{with} \quad D(x) = \begin{cases} 1, & |x| > L \\ d > 0, & |x| < L \end{cases}$$

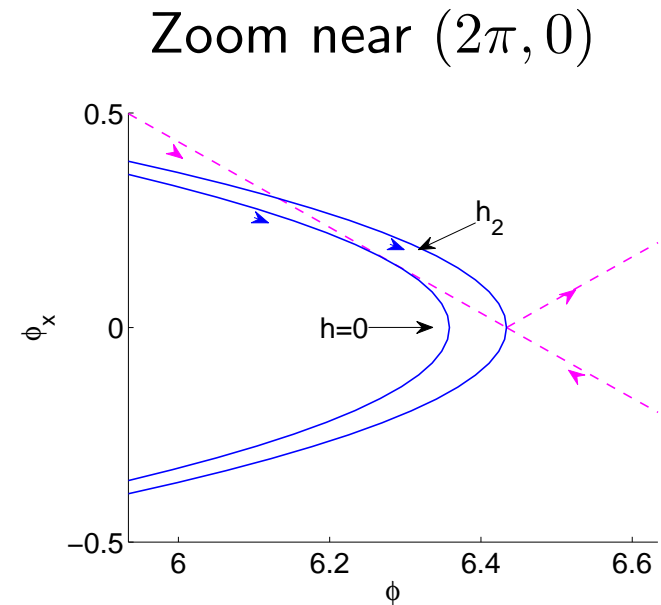
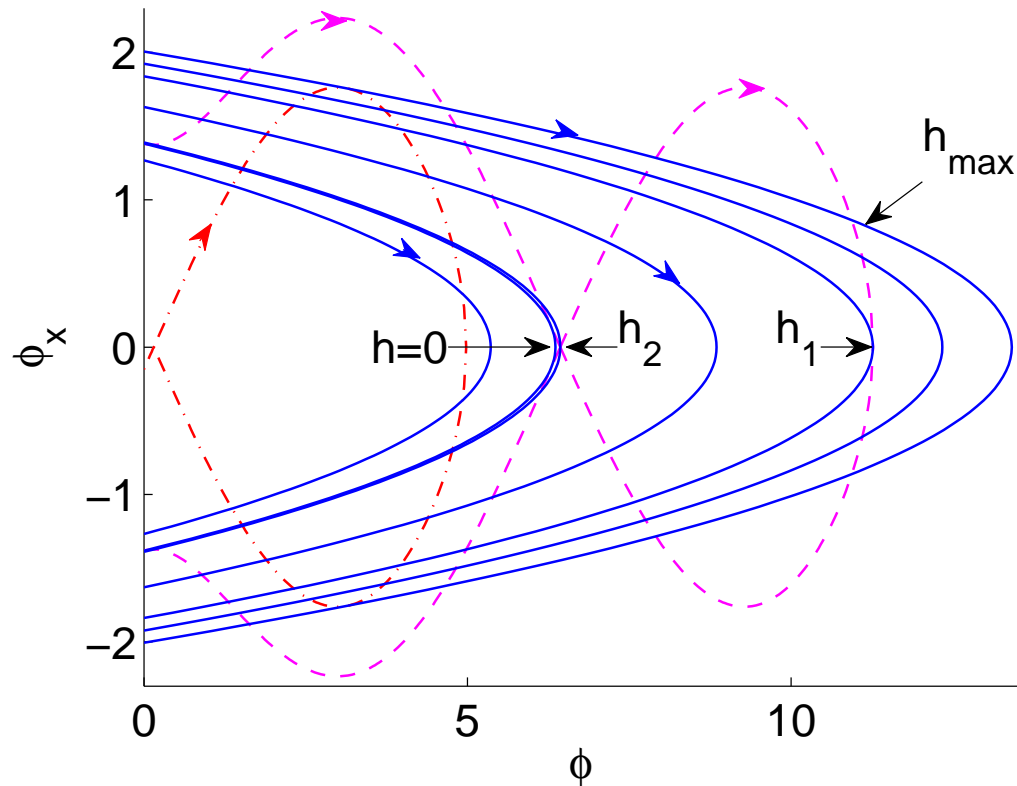
We focus on the existence and stability of stationary (pinned) fluxons.

- A pinned fluxon connects $(\arcsin \gamma)$ with $(2\pi + \arcsin \gamma)$.
- Stationary solutions satisfy $0 = \phi_{xx} - D(x) \sin \phi + \gamma$.
This is a spatially Hamiltonian system with Hamiltonian
$$H = \frac{1}{2}(\phi_x)^2 - D(x)(1 - \cos \phi) + \gamma \phi.$$
- Hamiltonian H is conserved on $(-\infty, -L)$, $(-L, L)$, (L, ∞) :
 - ◆ On $(-\infty, -L)$ and (L, ∞) , H is determined by the fixed points;
 - ◆ On $(-L, L)$, the H -value depends on the length L , denote by $h(L)$.

Existence of pinned fluxons

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$$\gamma = 0.15, d = 0$$



Red: leaving $\arcsin \gamma$ (unstable manifold);

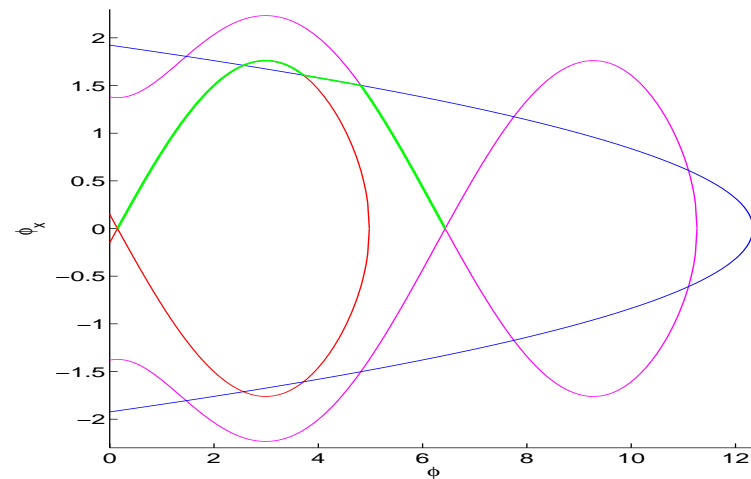
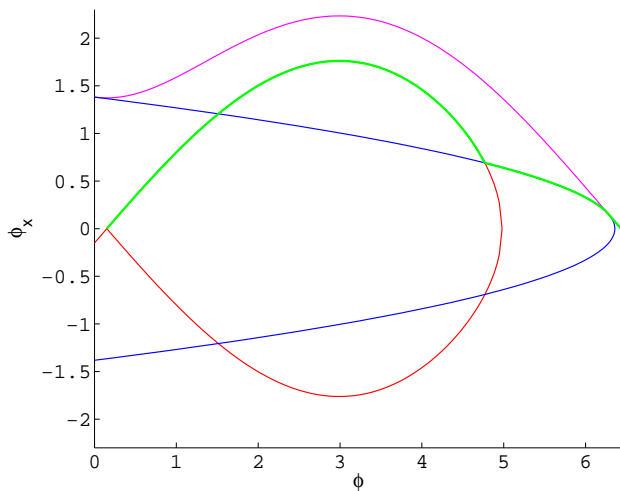
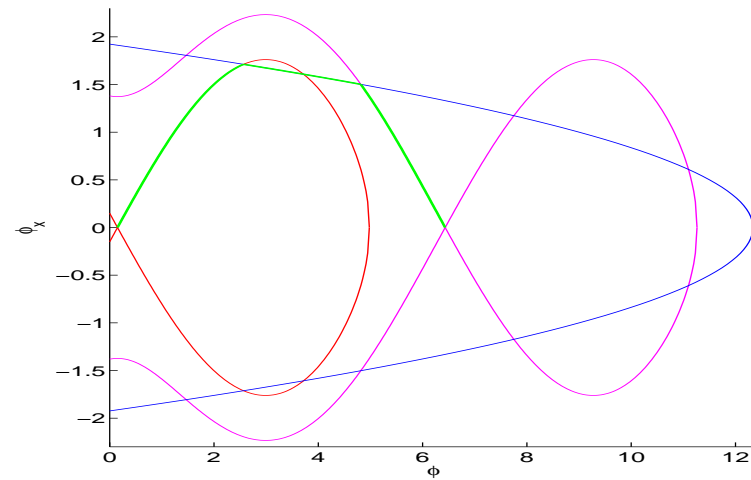
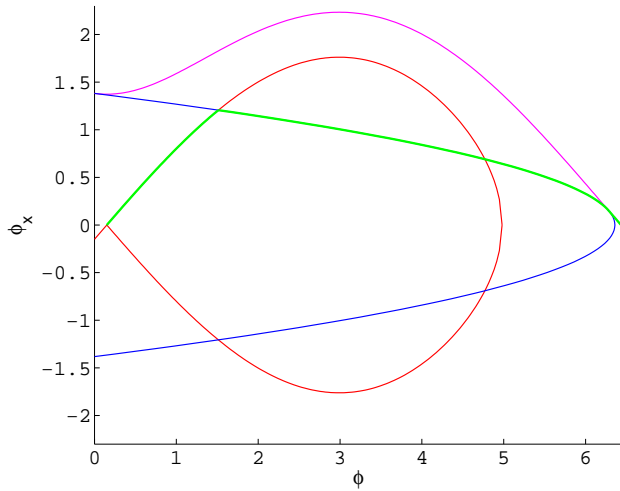
Magenta: returning to $2\pi + \arcsin \gamma$ (stable manifold);

Blue: dynamics for $d = 0$.

Monotonic pinned fluxons

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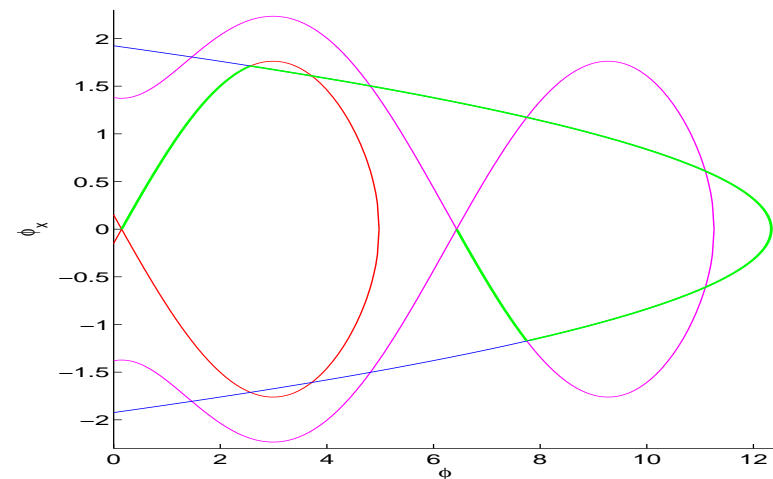
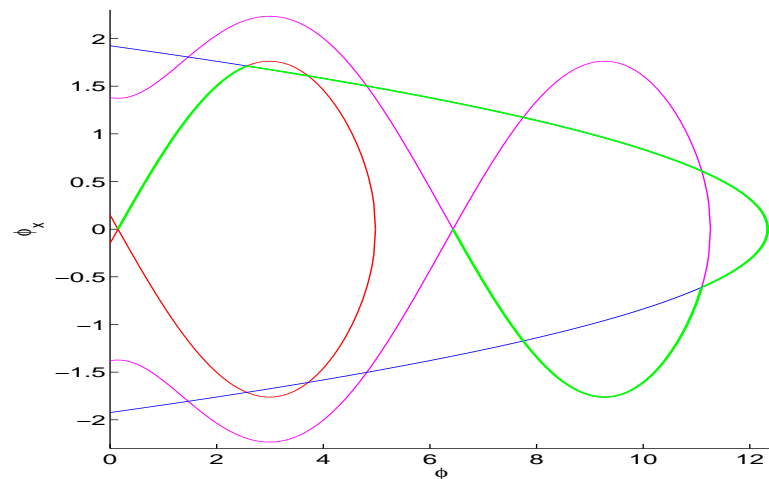
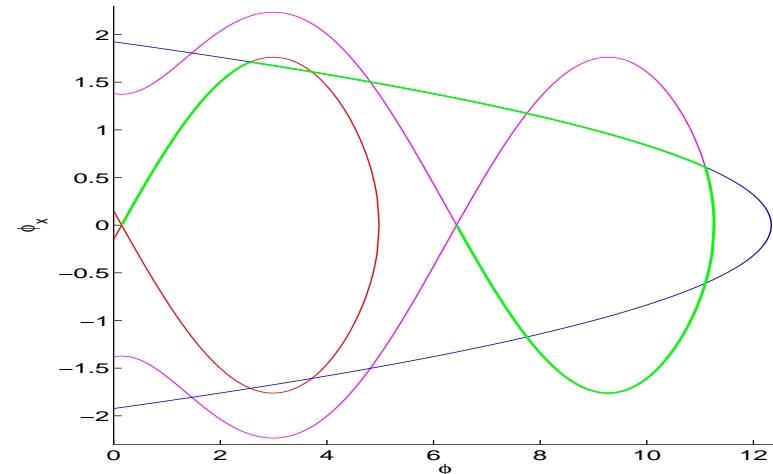
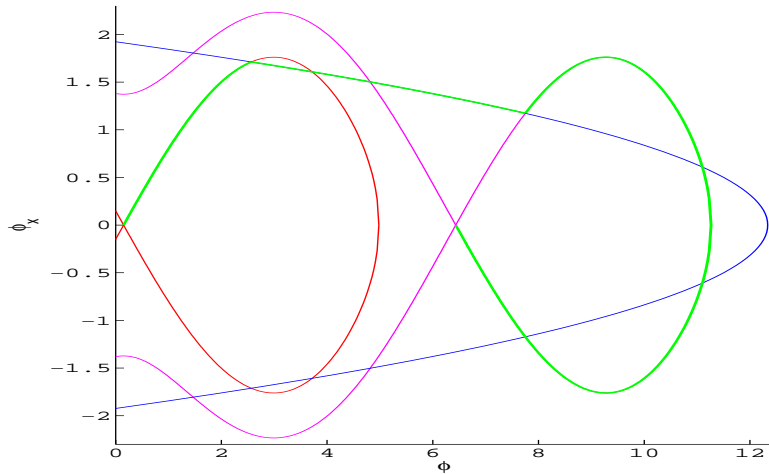
Two monotonic fluxons for $h = 0$: Two monotonic fluxons for $h = \frac{h_1 + h_{\max}}{2}$:



Other pinned fluxons

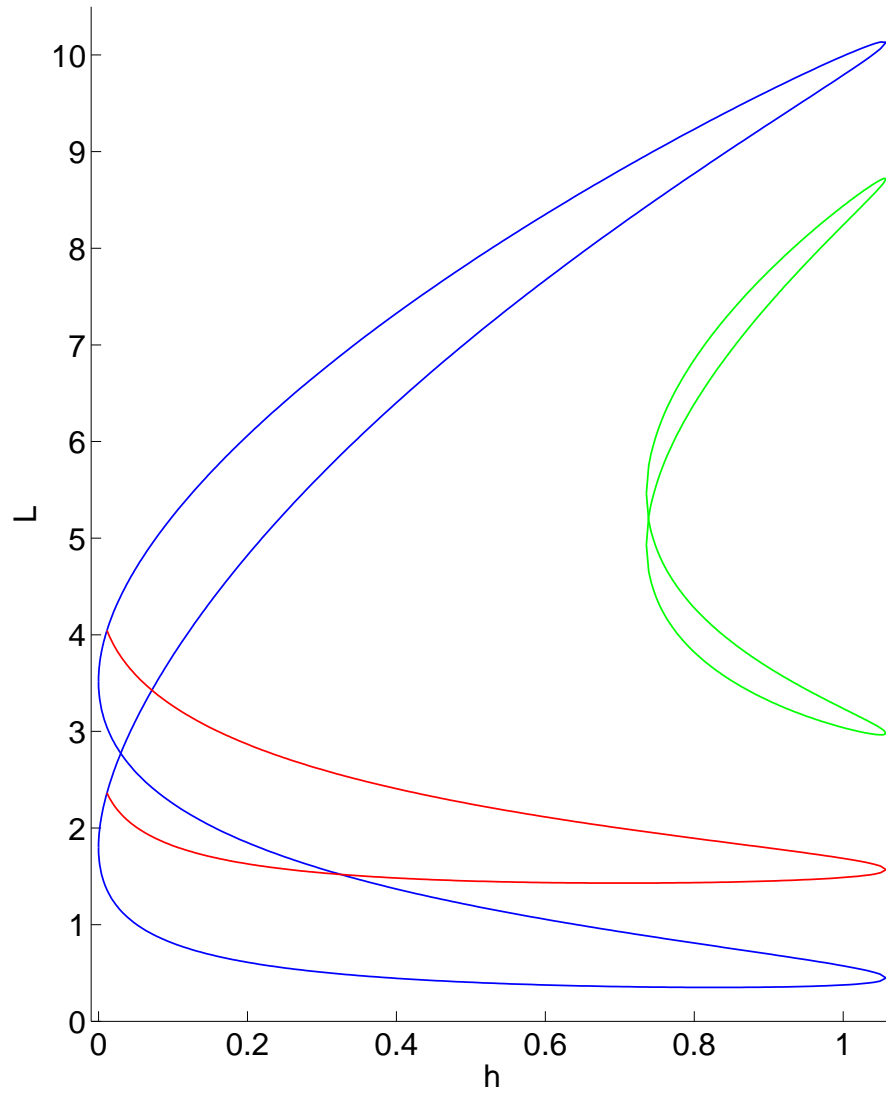
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Eight non-monotonic fluxons for $h = (h_1 + h_{\max})/2$ (four shown):



Impurity lengths, $\gamma = 0.15$, $d = 0$

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Observations:

- There is strictly positive minimum length and maximum length;
- For a fixed length, there are up to five pinned fluxons.
- Most fluxons are non-monotonic

How about stability??

[DERKS, DOELMAN, KNIGHT, SUSANTO (2012)]

Wave equation with one inhomogeneity

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Consider a wave equation with one finite length inhomogeneity

$$u_{tt} = u_{xx} + \frac{\partial V}{\partial u}(u, x; L), \text{ where } V(u, x; L) = \begin{cases} V_l(u), & x < -L; \\ V_m(u), & -L < x < L; \\ V_r(u), & x > L. \end{cases}$$

Assumptions:

- Hamiltonian equations with outer potentials $V_l(u)$ and $V_r(u)$ have fixed points, called $u_{-\infty}$ resp. u_{∞} , which are saddles in the spatial dynamics (stable in temporal dynamics).
- There is an interval of L -values for which there exist stationary fronts connecting $u_{-\infty}$ and u_{∞} . The L -values and the fronts can be parametrised by

$$h = \frac{1}{2}\hat{u}_x^2 + V_m(\hat{u}), \quad 0 < x < L;$$

where $\hat{u}(x; h)$ is the front.

Stability and the L - h curve

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Linearisation about a front $\hat{u}(x; h)$ gives (using $u(x, t) = \hat{u}(x; h) + e^{\lambda t} v(x)$):

$$\lambda(\lambda - \alpha)v = \mathcal{L}(h)v, \text{ with } \mathcal{L}(h) = D_{xx} + \frac{\partial^2 V}{\partial u^2}(\hat{u}(x; h), x; L(h)).$$

Theorem [KNIGHT, DERKS, DOELMAN, SUSANTO (2013)] *If the solution $\hat{u}(x; h)$ is such that $\hat{u}_x \neq 0$ on the middle interval, then its linearisation operator $\mathcal{L}(h)$ has an eigenvalue zero in $H^2(\mathbb{R})$ if and only if*

$$[V'_m(\hat{u}_l(h)) - V'_l(\hat{u}_l(h))] p_l(h) [V'_m(\hat{u}_r(h)) - V'_r(\hat{u}_r(h))] p_r(h) \mathbf{L}'(\mathbf{h}) = 0.$$

where $\hat{u}_l(h) = \hat{u}(0; h)$, $p_l(h) = \hat{u}_x(0; h)$,
 $\hat{u}_r(h) = \hat{u}(L(h); h)$, $p_r(h) = \hat{u}_x(L(h); h)$.

- Bifurcation points if $[V'_m(\hat{u}_l(h)) - V'_l(\hat{u}_l(h))] \rightarrow 0$, or $p_l(h) \rightarrow 0$, etc. and then $L'(h) \rightarrow \infty$.
- For “most” fronts, the stability criterion is $\mathbf{L}'(\mathbf{h}) = 0$.

Ideas behind the proof

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- Get a compatibility condition for the existence of an eigenvalue zero by using that the eigenfunction will consist of linear combinations of

$$\hat{u}_x \quad \text{and} \quad \hat{u}_x \int \frac{dx}{(\hat{u}_x(x))^2},$$

which have to be patched together smoothly (C^1) at the points $x = -L$ and $x = L$.

- In the simplest case, $u_x(u, h) = \sqrt{2[h - V_m(u)]}$ and

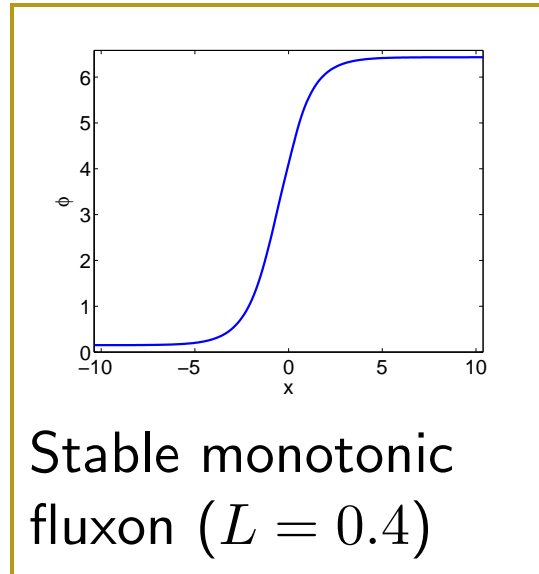
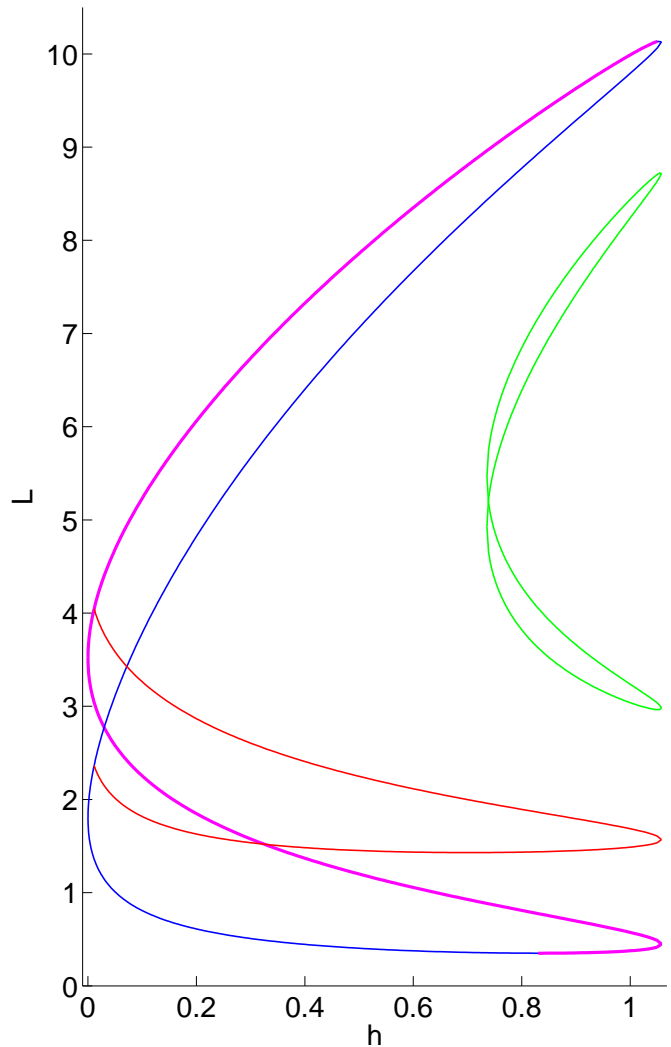
$$L(h) = \int_{\hat{u}_l(h)}^{\hat{u}_r(h)} \frac{du}{\sqrt{2[h - V_m(u)]}}.$$

For more complex functions \hat{u} , the length consists of sums of similar integrals.

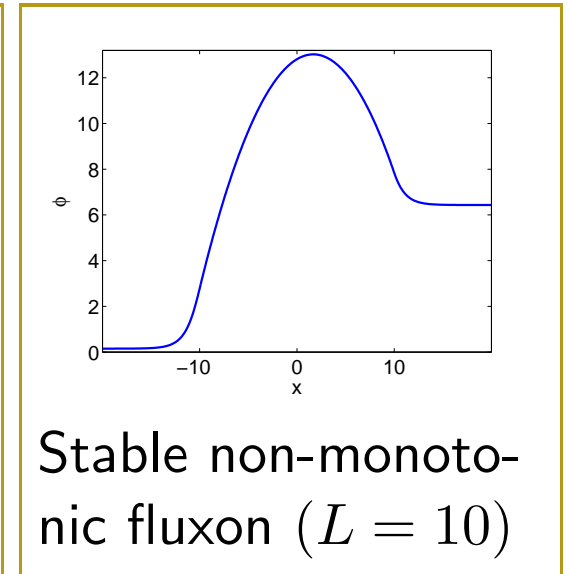
- Relate the derivative of the length curve $L(h)$ to compatibility condition.

Stability in long JJ with impurity

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Stable monotonic fluxon ($L = 0.4$)



Stable non-monotonic fluxon ($L = 10$)

For each length, there is exactly one stable pinned fluxon: they are on the magenta curve.

- Full proof uses continuity via $(\gamma, d) = (0, 0)$;
- Nonlinear stability can be shown via the Hamiltonian.

Wave equation with N inhomogeneities

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Consider a wave equation with N inhomogeneities

$$u_{tt} = u_{xx} + \frac{\partial V}{\partial u}(u, x), \text{ where } V(u, x) = \begin{cases} V_l(u), & x < \chi_0; \\ V_1(u), & \chi_0 < x < \chi_1; \\ \vdots & \vdots \\ V_N(u), & \chi_{N-1} < x < \chi_N; \\ V_r(u), & x > \chi_N. \end{cases}$$

Assumptions:

- Hamiltonian equations with outer potentials $V_l(u)$ and $V_r(u)$ have fixed points, called $u_{-\infty}$ resp. u_{∞} , which are saddles in the spatial dynamics.
- There is region of $L_i = \chi_i - \chi_{i-1}$ -values for which there exist stationary fronts connecting $u_{-\infty}$ and u_{∞} . The L_i -values and the fronts can be parametrised by

$$h_i = \frac{1}{2}\widehat{u}_x^2 + V_i(\widehat{u}), \quad \chi_{i-1} < x < \chi_i, \quad i = 1, \dots, N,$$

where $\widehat{u}(x; h_1, \dots, h_N)$ denote the fronts.

Stability and the L_i - h_j surfaces

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Linearisation about a front $\hat{u}(x; \mathbf{h})$ gives (with $\mathbf{h} = (h_1, \dots, h_N)$)

$$\lambda(\lambda - \alpha)v = \mathcal{L}(\mathbf{h})v, \text{ with } \mathcal{L}(\mathbf{h}) = D_{xx} + \frac{\partial^2 V}{\partial u^2}(u(x; \mathbf{h}); L(\mathbf{h})).$$

Theorem [KNIGHT, DERKS, DOELMAN, SUSANTO (2013)] *If the solution $\hat{u}(x; \mathbf{h})$ is such that $\hat{u}_x \neq 0$ on any interval, then its linearisation operator $\mathcal{L}(\mathbf{h})$ has an eigenvalue zero if and only if*

$$\det(\Gamma_N) \prod_{i=0}^N \mathcal{B}_i = 0,$$

where

$$\begin{aligned} \mathcal{B}_i(\mathbf{h}) &= [V'_{i+1}(\hat{u}(\chi_i)) - V'_i(\hat{u}_i(\chi_i))] \hat{u}_x(\chi_i), \quad i = 1, \dots, N-1 \\ \mathcal{B}_0(\mathbf{h}) &= [V'_1(\hat{u}_m(\chi_0)) - V'_l(\hat{u}_m(\chi_0))] \hat{u}_x(\chi_0), \\ \mathcal{B}_N(\mathbf{h}) &= [V'_r(\hat{u}(\chi_N)) - V'_N(\hat{u}(\chi_N))] \hat{u}_x(\chi_N) \end{aligned}$$

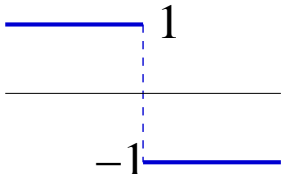
and

$$\Gamma_N = \frac{\partial(L_1, \dots, L_N)}{\partial(h_1, \dots, h_N)} = \begin{pmatrix} \frac{\partial L_1}{\partial h_1} & \mathcal{B}_1^{-1} & 0 & \dots & 0 \\ \mathcal{B}_1^{-1} & \frac{\partial L_2}{\partial h_2} & \mathcal{B}_2^{-1} & \ddots & 0 \\ 0 & \mathcal{B}_2^{-1} & \ddots & \ddots & \\ \vdots & & \ddots & & \mathcal{B}_{N-1}^{-1} \\ 0 & 0 & \dots & \mathcal{B}_{N-1}^{-1} & \frac{\partial L_N}{\partial h_N} \end{pmatrix}, \quad \text{as } \mathcal{B}_i^{-1} = \frac{\partial L_{i+1}}{\partial h_i} = \frac{\partial L_i}{\partial h_{i+1}}.$$

A $0-\pi$ junction with impurity

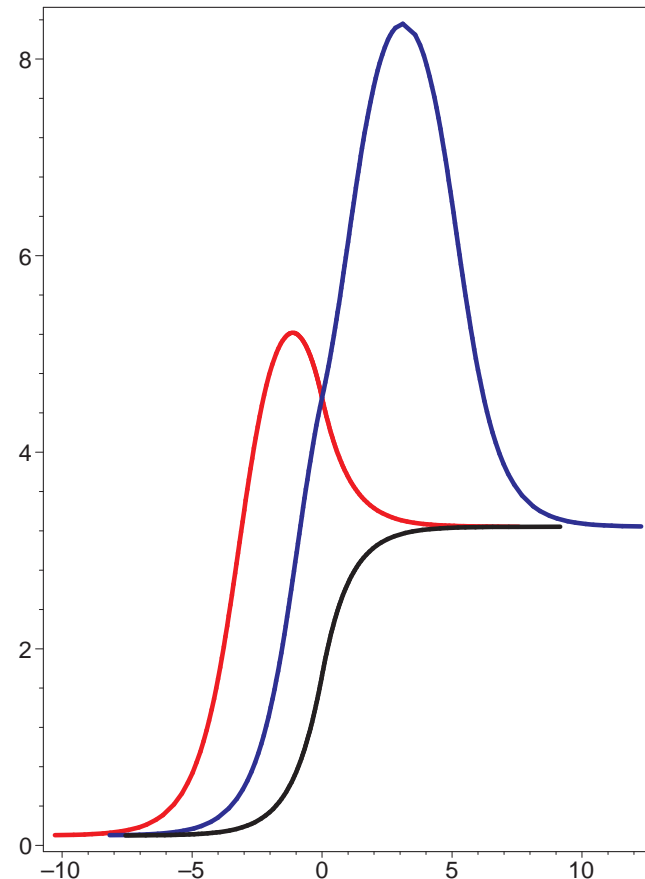
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A $0-\pi$ junction is given by

$$\phi_{tt} = \phi_{xx} - D(x) \sin \phi + \gamma - \alpha \phi_t, \text{ with } D(x) = \begin{cases} 1, & x < L_2 \\ -1, & x > L_2 \end{cases}$$


It can be shown that there are three types of stationary fluxons (see right, used $L_2 = 0$).

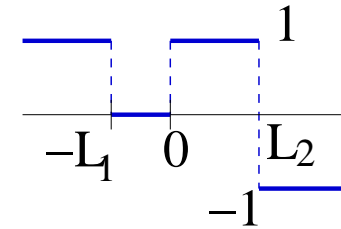
The black π -fluxon is unstable and the red and blue ones are unstable (red one marginally unstable if $\gamma \approx 0$).



Stabilization of π -fluxon by impurity

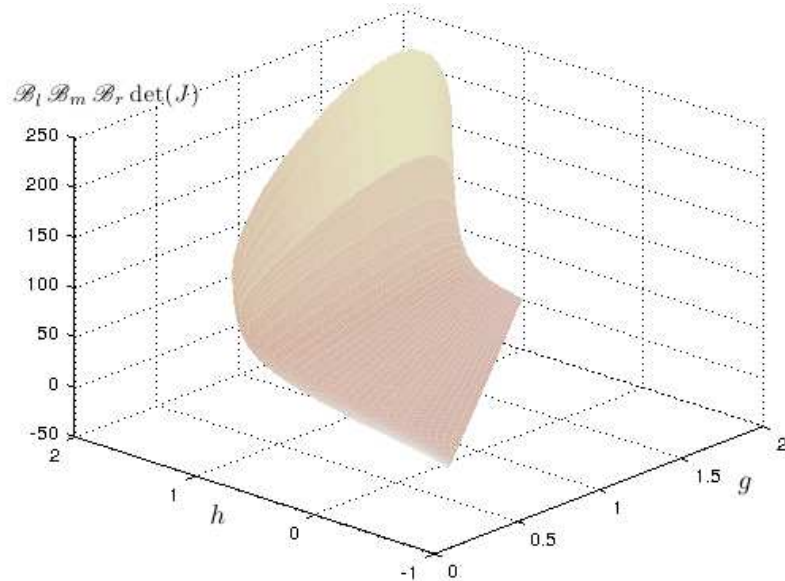
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Now add an impurity with $d = 0$ on the left of the junction, does this stabilise the red π -fluxon?

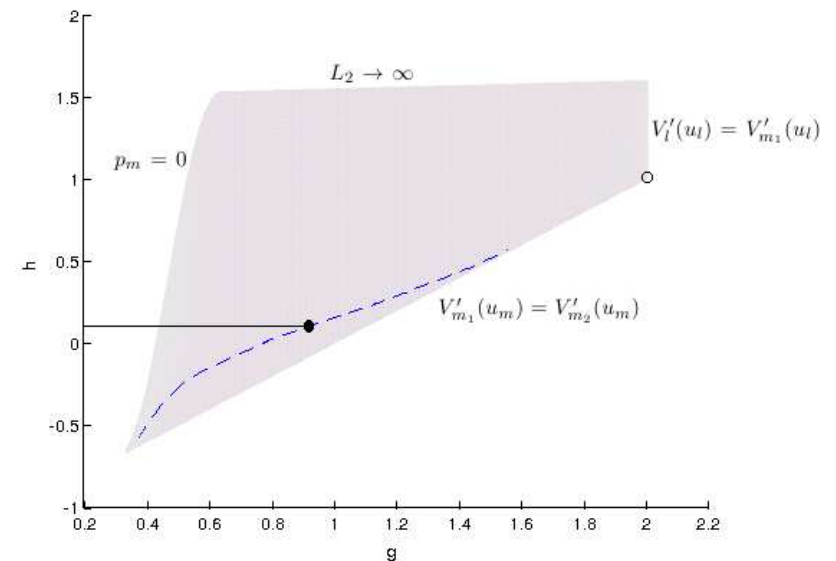


We have a wave equation with 2 inhomogeneties (N=2):

Sketch of $\Gamma_2 = \det \left[\frac{\partial(L_1, L_2)}{\partial(h_1, h_2)} \right]$ for $\gamma = 0.1$:



The curve $\det \left[\frac{\partial(L_1, L_2)}{\partial(h_1, h_2)} \right] = 0$:

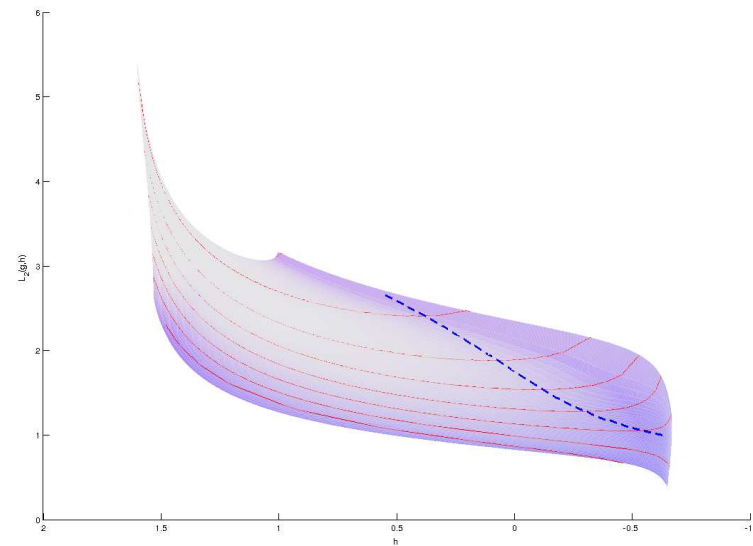
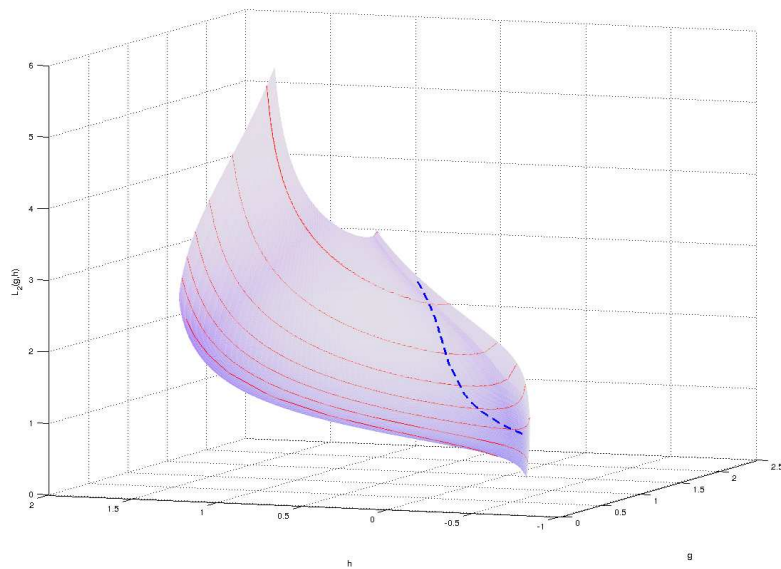


Eigenfunctions without zeros on the zero curve: red π -fluxon is stabilised by impurity

Link with one inhomogeneity theorem

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- If one of the two lengths are fixed, then we are in the situation of one inhomogeneity. Fixing one length (say L_1), leads to a curve $h_1(h_2)$.
- The theorem for one inhomogeneity checks for a extremal point of $L_2(h_1(h_2), h_2)$ with $h_1(h_2)$ given by $L_1(h_1, h_2) = \text{const}$. It turns out that this is the condition that the determinant vanishes at a point on the curve $h_1(h_2)$.



Yakushevich model for DNA dynamics

Introduction sG Stability DNA Discussion

Assumptions and notation:

- The DNA is homogeneous, the sugar-phosphate backbone (SPB) doesn't move, the only dynamics are the nitrogen base rotations. The rotation angle of the base n on the “ \pm ” (red/blue) chain, away from the equilibrium, is denoted ϕ_n^\pm .

- Interactions are modelled by potentials:

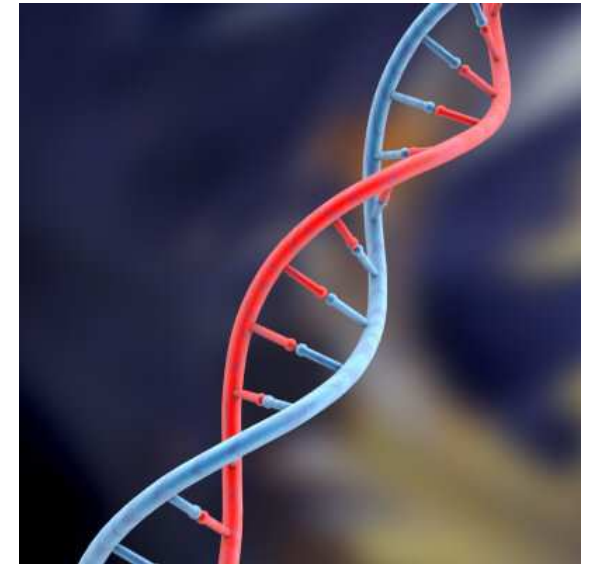
- ◆ a *stacking* potential $\widehat{V}_s(\phi_{n+1}^\pm, \phi_n^\pm)$:

$$\widehat{V}_s(\phi_{n+1}^\pm, \phi_n^\pm) = \frac{K_s}{2} (\phi_{n+1}^\pm - \phi_n^\pm)^2;$$

- ◆ a *pairing* potential $\widehat{V}_p(\phi_n^+, \phi_n^-)$:

$$\widehat{V}_p(\phi_n^+, \phi_n^-) = \frac{K_p}{2} r^2 \left[(2 - \cos \phi_n^+ - \cos \phi_n^-)^2 + (\sin \phi_n^+ + \sin \phi_n^-)^2 \right].$$

- The kinetic energy of a base is $\widehat{T} = \frac{I}{2} (\dot{\phi}_n^\pm)^2$.



From:

<http://www.csb.yale.edu/>

The continuum Y-model

Introduction sG Stability DNA Discussion

- Change of coordinates: $\psi_n = (\phi_n^+ + \phi_n^-) / 2$ and $\chi_n = (\phi_n^+ - \phi_n^-) / 2$.
- The distance δ between the base sites is small: assume interpolating fields $\psi(x, t)$ and $\chi(x, t)$ with $\psi(n\delta, t) = \psi_n(t)$ and $\chi(n\delta, t) = \chi_n(t)$.
- The equations of motion are

$$\psi_{tt} = \kappa_s \psi_{xx} - \kappa_p \sin \psi \cos \chi - \mu \psi_t;$$

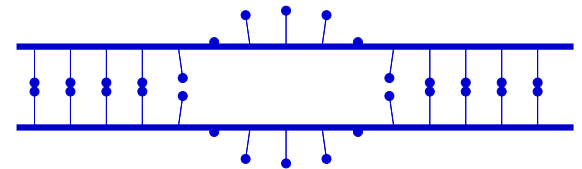
$$\chi_{tt} = \kappa_s \chi_{xx} - \kappa_p \sin \chi (\cos \psi - \cos \chi) - \mu \chi_t.$$

where $\kappa_s = K_s \delta^2 / I$, $\kappa_p = K_p r^2 / I$, and μ is the dissipation coefficient.

- The symmetric configuration $\chi = 0$ is invariant and gives the (**damped**) sine-Gordon equation

$$\psi_{tt} = \kappa_s \psi_{xx} - \kappa_p \sin \psi - \mu \psi_t$$

and has a family of travelling soliton solutions ($\mu = 0$).



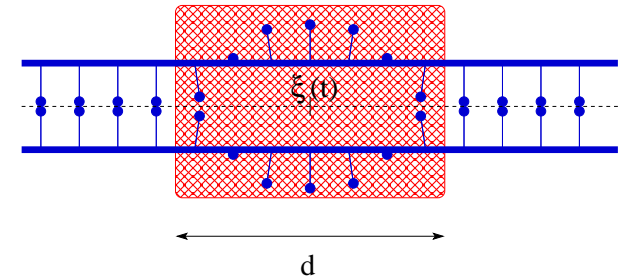
- Similar for the anti-symmetric configuration with $\psi = 0$ (double sG).

Including the interaction with RNAP

Introduction sG Stability DNA Discussion

- Assumptions:

- ◆ RNAP is present on DNA chain;
- ◆ RNAP acts locally on DNA;
- ◆ RNAP moves by pulling on DNA chain;
- ◆ There is sufficient ATP to feed RNAP.



- Write $\xi(t)$ for the centre of the RNAP and d for the radius of the region of binding with the DNA, i.e., the fields feel the RNA for $\xi - d < x < \xi + d$. The interaction potential is

$$W(\phi, x, \xi) = W_0(\phi) R(\xi, x), \quad \text{with} \quad R(\xi, x) = \begin{cases} 1, & |x - \xi| < d \\ 0, & |x - \xi| > d \end{cases}$$

- The interaction potential $W_0(\phi)$ should keep the DNA open, thus $\phi = \pi$ should be a stable equilibrium. We will use $W_0(\phi) = K_r \cos \phi$.
- Constant RNAP pulling force P along the axis: $\xi_{tt} = P - \nu \xi_t$.

DNA-RNAP interaction dynamics

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The DNA-RNAP interaction gives for the equations of motion

$$\psi_{tt} = \kappa_s \psi_{xx} - [\kappa_p - \kappa_r R(\xi, x)] \sin \psi \cos \chi - \mu \psi_t;$$

$$\chi_{tt} = \kappa_s \chi_{xx} - \kappa_p \sin \chi (\cos \psi - \cos \chi) + \kappa_r R(\xi, x) \sin \chi \cos \psi - \mu \chi_t;$$

$$\xi_{tt} = P - \nu \xi_t.$$

Asymptotically, the RNAP moves with speed $c = P/\nu$, thus $\xi(t) = ct + \xi_0$.

Going to a moving frame $z = \frac{x - \xi(t)}{\sqrt{\kappa_s - c^2}}$ gives

$$\psi_{tt} - \frac{2\sigma}{\mu} \psi_{zt} + \mu \psi_t = \psi_{zz} - [\kappa_p - \kappa_r \rho(z)] \sin \psi \cos \chi - \sigma \psi_z;$$

$$\chi_{tt} - \frac{2\sigma}{\mu} \chi_{zt} + \mu \chi_t = \chi_{zz} - \kappa_p \sin \chi (\cos \psi - \cos \chi) + \kappa_r \rho(z) \sin \chi \cos \psi - \sigma \chi_z;$$

$$\text{with } \rho(z) = \begin{cases} 1, & |z| < \hat{d} \\ 0, & |z| > \hat{d} \end{cases}, \quad \hat{d} = \frac{d}{\sqrt{\kappa_s - c^2}} \quad \text{and} \quad \sigma = \frac{\mu c}{\sqrt{\kappa_s - c^2}}.$$

Undamped symmetric travelling kinks

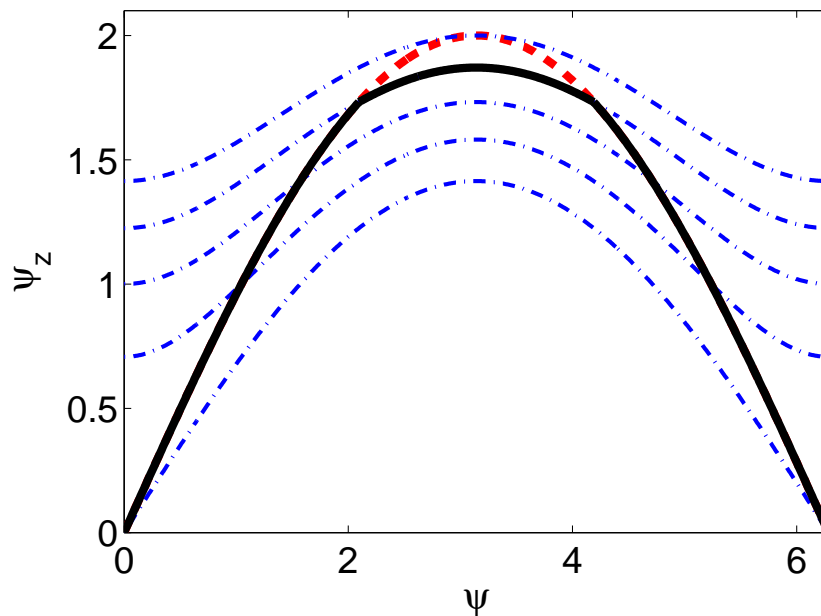
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Kink equations for the symmetric solutions:

$$\begin{aligned}\psi_{zz} &= \kappa_p \sin \psi - \sigma \psi_z, & |z| > \hat{d}; \\ \psi_{zz} &= [\kappa_p - \kappa_r] \sin \psi - \sigma \psi_z, & |z| < \hat{d}.\end{aligned}$$

No damping ($\sigma = 0$), $\kappa_r < \kappa_p$

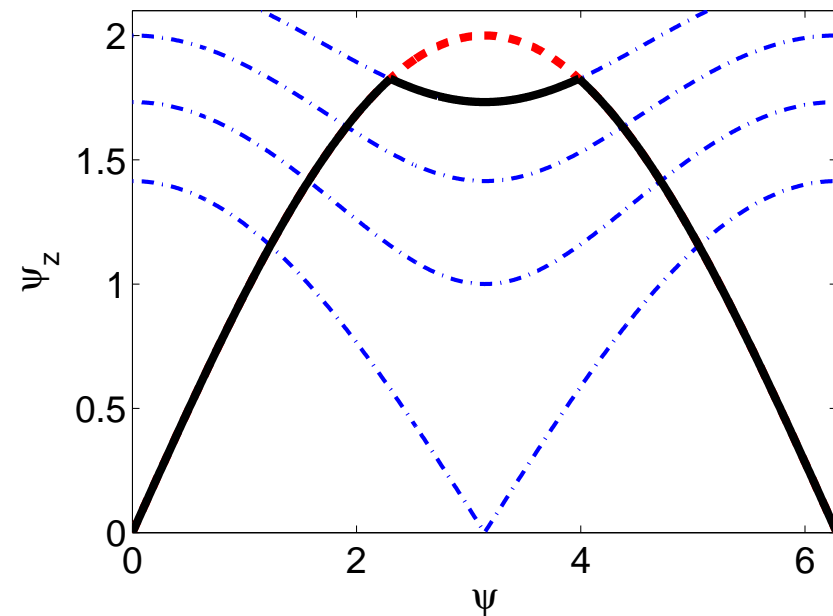
$\kappa_p=1, \kappa_r=0.5, \sigma=0$



Exist for any $\hat{d} > 0$

No damping ($\sigma = 0$), $\kappa_r > \kappa_p$

$\kappa_p=1, \kappa_r=0.5, \sigma=0$



Exist for any $\hat{d} > 0$

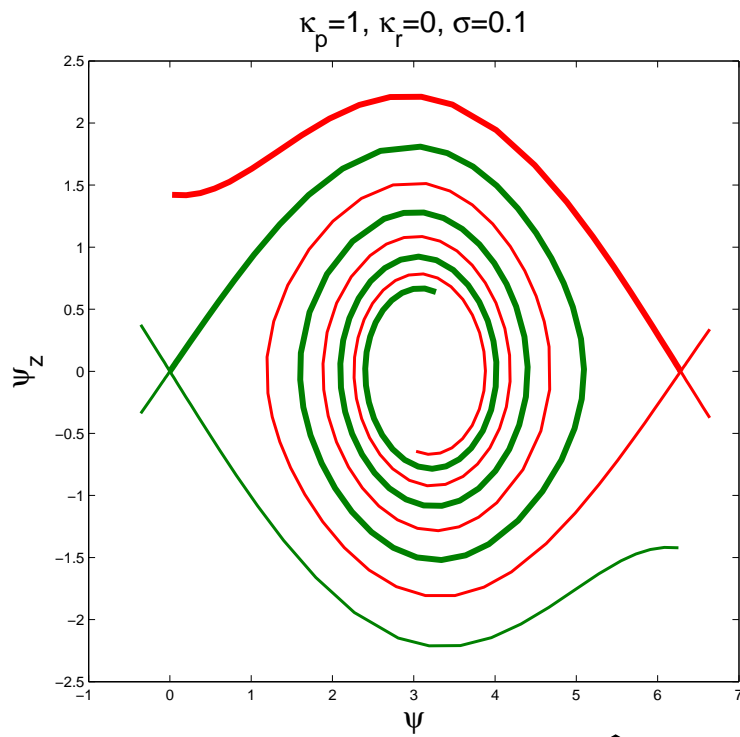
Damped symmetric travelling kinks

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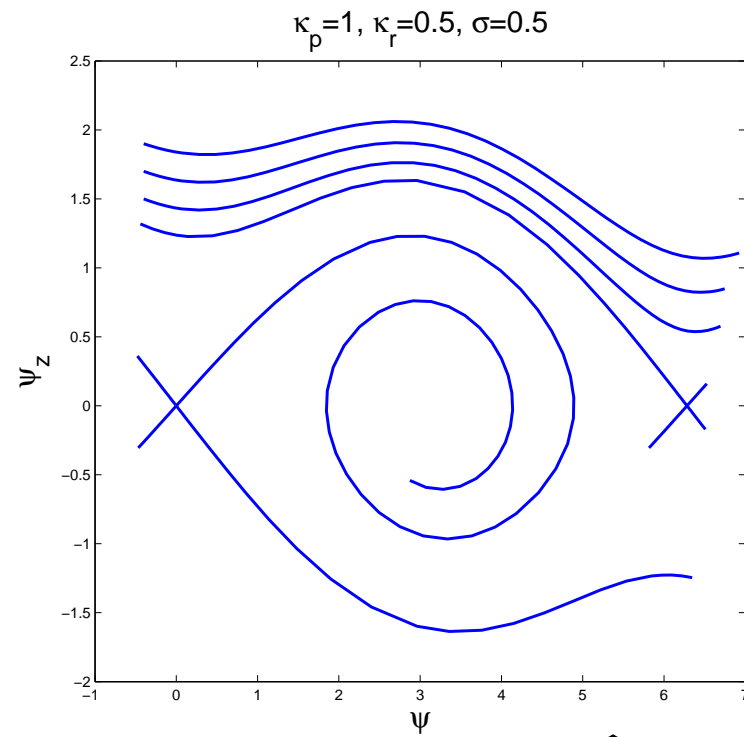
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Damped ($\sigma > 0$), $\kappa_r < \kappa_p$:



Outer: $|z| > \hat{d}$



Inner: $|z| < \hat{d}$

Damped symmetric travelling kinks

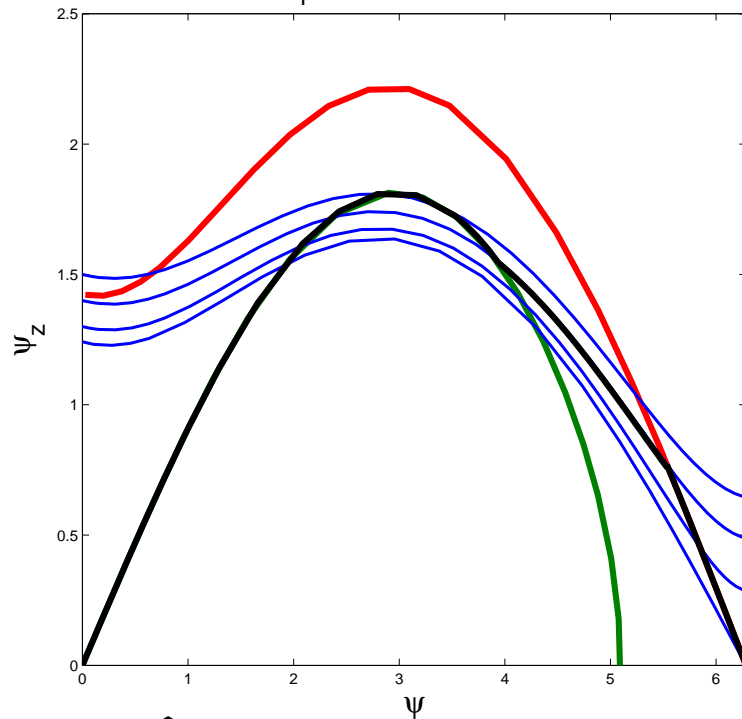
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Kink equations for the symmetric solutions:

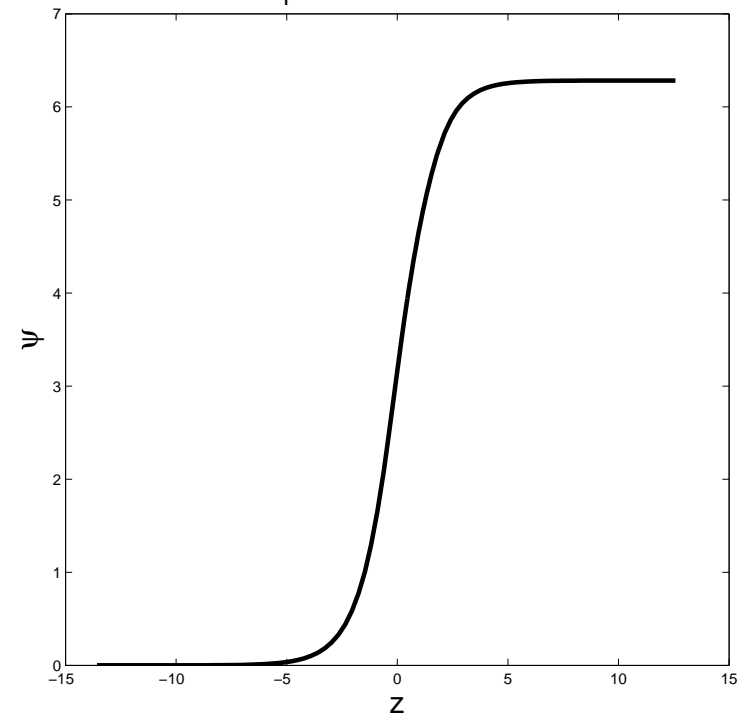
$$\begin{aligned}\psi_{zz} &= \kappa_p \sin \psi - \sigma \psi_z, & |z| > \hat{d}; \\ \psi_{zz} &= [\kappa_p - \kappa_r] \sin \psi - \sigma \psi_z, & |z| < \hat{d}.\end{aligned}$$

Damped ($\sigma > 0$), $\kappa_r < \kappa_p$:

$\kappa_p=1, \kappa_r=0.5, \sigma=0.1$



$\kappa_p=1, \kappa_r=0.5, \sigma=0.1$



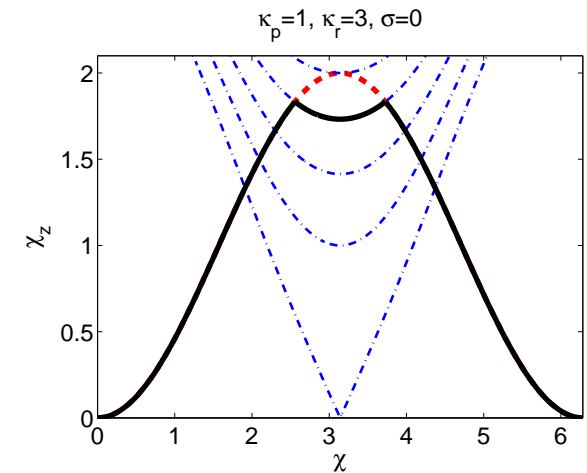
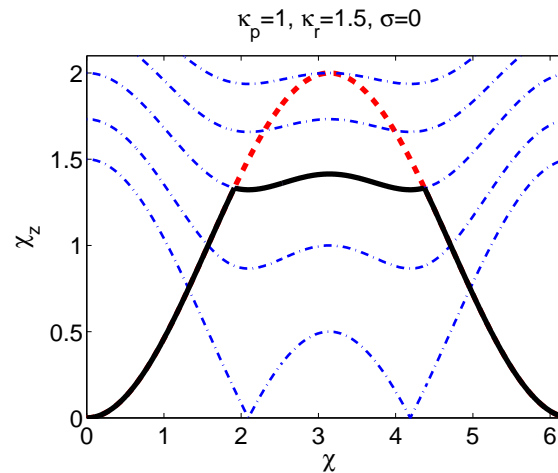
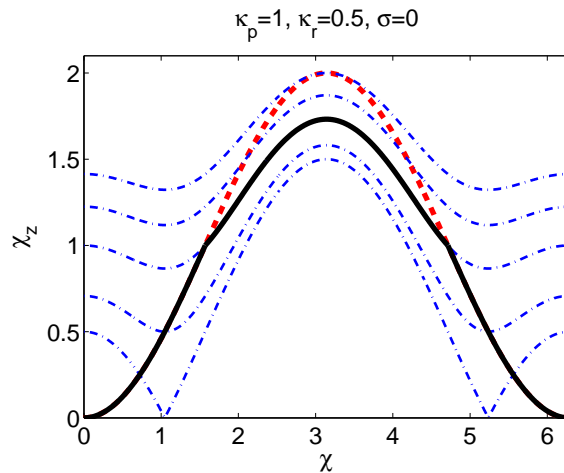
Exist for \hat{d} not too small and similar for $\kappa_r > \kappa_p$.

Anti-symmetric travelling kinks

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Equations for the anti-symmetric solutions:

$$\begin{aligned} \chi_{zz} &= \kappa_p \sin \chi (1 - \cos \chi) - \sigma \psi_z, & |z| > \hat{d}; \\ \chi_{zz} &= \sin \chi [(\kappa_p - \kappa_r) - \kappa_p \cos \chi] - \sigma \psi_z, & |z| < \hat{d}. \end{aligned}$$



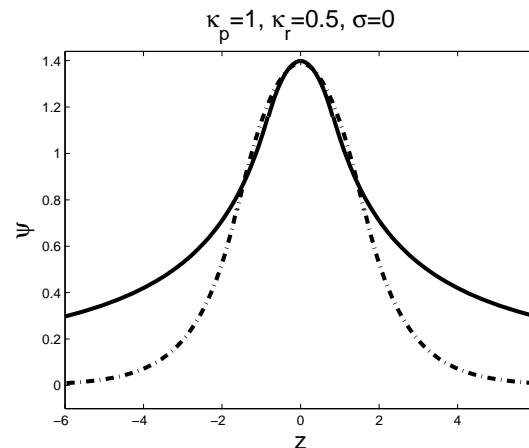
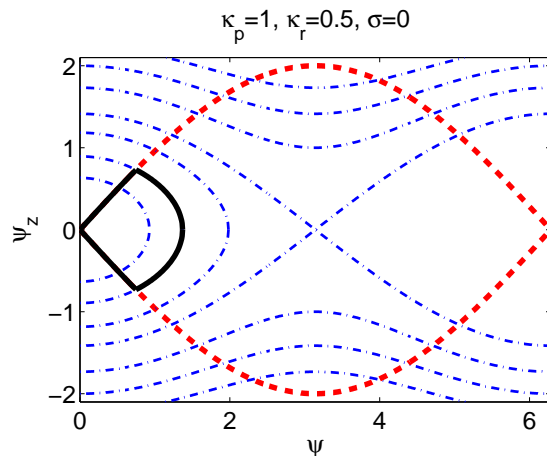
- Undamped kinks exist for any $\hat{d} > 0$;
- Damped kinks exist for \hat{d} not too small

Undamped travelling solitons

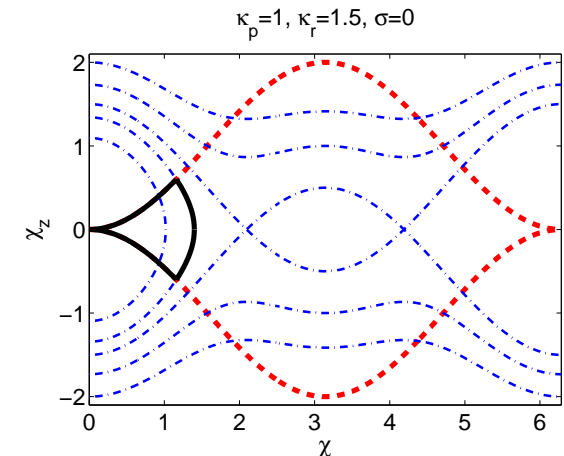
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New soliton solutions:

Symmetric



Anti-symmetric

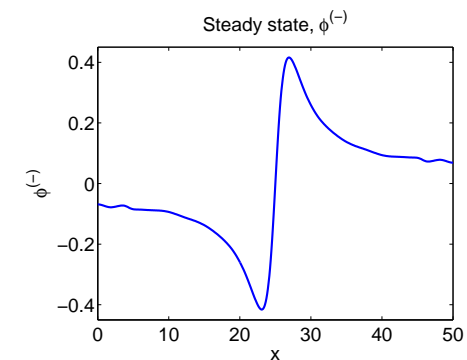
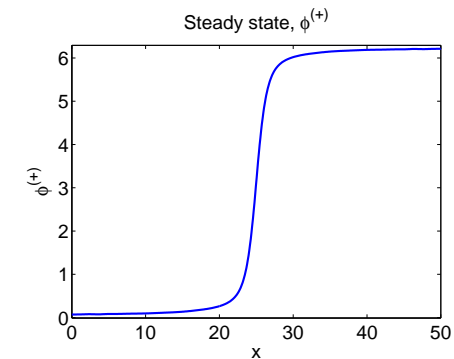
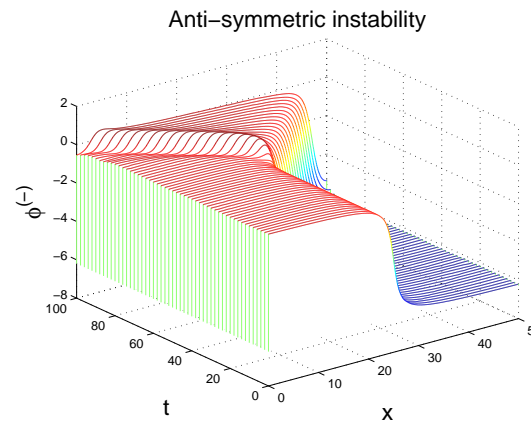
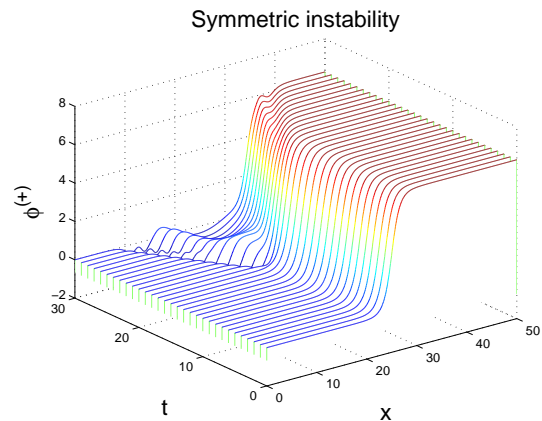


- In the symmetric section (left), solitons exist for $\kappa_r > \kappa_p$ and any $\hat{d} > 0$;
- In the anti-symmetric section (right), these solitons exist always.
- Middle plot show the soliton shapes, the dashed curve is the symmetric one, the solid curve the anti-symmetric one.

Kink stability

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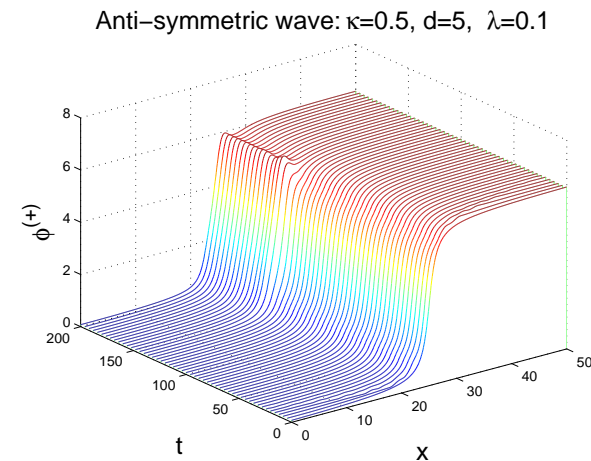
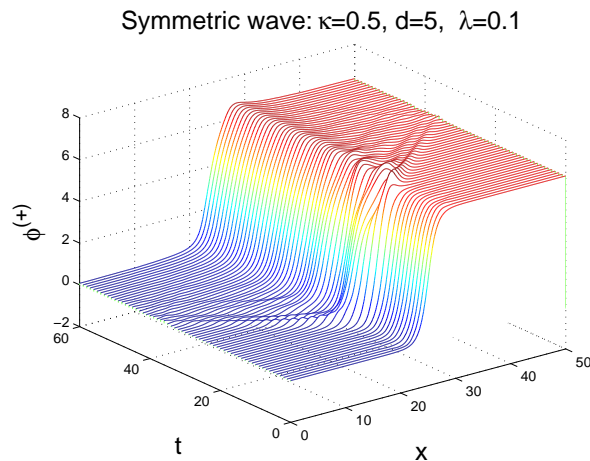
- Without the RNAP the symmetric and anti-symmetric kinks are stable in their own invariant sub space, but unstable under symmetry breaking perturbations.



Kink stability

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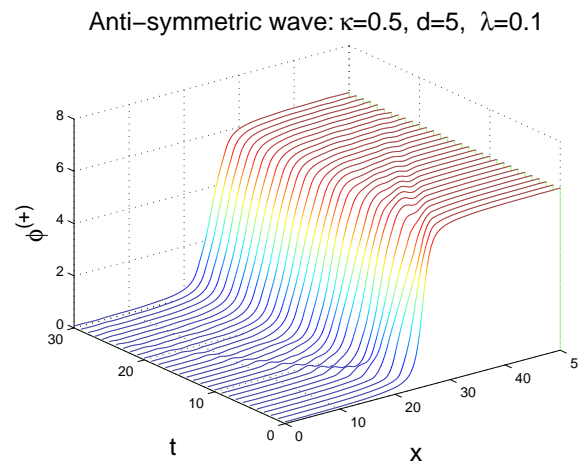
- Without the RNAP the symmetric and anti-symmetric kinks are stable in their own invariant sub space, but unstable under symmetry breaking perturbations.
- The RNAP and dissipation have a stabilising effect on the symmetric and anti-symmetric kink.



Kink stability

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- Without the RNAP the symmetric and anti-symmetric kinks are stable in their own invariant sub space, but unstable under symmetry breaking perturbations.
- The RNAP and dissipation have a stabilising effect on the symmetric and anti-symmetric kink.
- The a-symmetric stable kink undergoes a tiny modification due to the RNAP and stays stable.

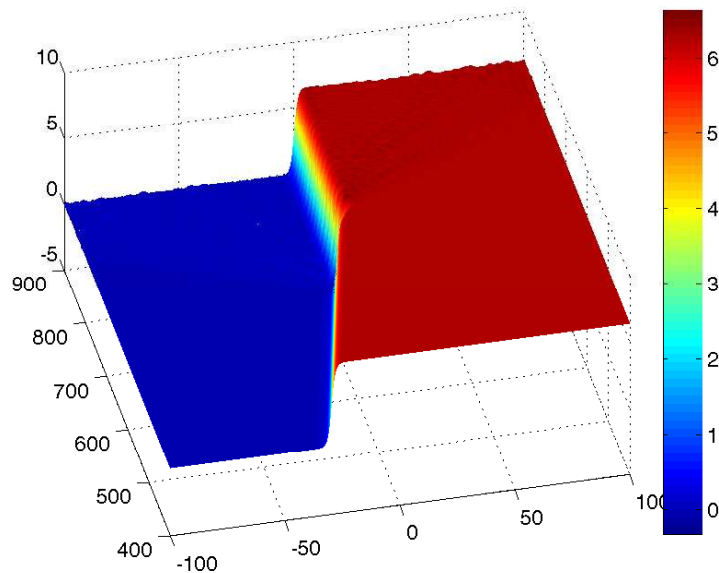


[DERKS, GAETA (2011)]

Conclusion and discussion

Introduction sG Stability DNA Discussion

- For the Josephson junctions we showed existence and stability of stationary fluxons for one and more inhomogeneities. The stability results are valid for general inhomogeneous wave equations.
- In the Josephson junctions, how do travelling fluxons interact with the stationary ones or an inhomogeneity?



Projecting onto families of sine-Gordon-type fluxons could be a good avenue.



Conclusion and discussion



Introduction sG Stability DNA Discussion

- For the Josephson junctions we showed existence and stability of stationary fluxons for one and more inhomogeneities. The stability results are valid for general inhomogeneous wave equations.
- In the Josephson junctions, how do travelling fluxons interact with the stationary ones or an inhomogeneity? Some results can be derived by projecting onto families of sine-Gordon-type fluxons.
- Can we extend the theory to the existence and stability of pinned fronts in coupled inhomogeneous wave equations? This is needed in the DNA-RNAP models.



Some other researchers in the UK



Introduction sG Stability DNA Discussion

Some other researchers at UK universities working in related areas:

Aston: Sergei Turitsyn

Bath: Karsten Matthies, Johannes Zimmer

Heriott Watt: Margot Beck, Simon Malham, Noel Smyth

Loughborough: Gennady El, Roger Grimshaw, Karima Khusnutdinova

Nottingham: Hadi Susanto

Oxford: Mason Porter

Warwick: Claude Baesens, Robert MacKay

And many others

Thank you!